Work with

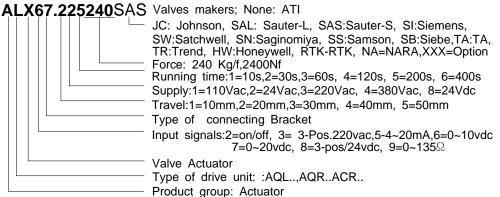
- Honeywell
- Johnson controls
- Siemens.. Many others

# **Multi-Con Valve Actuator**

0(2)~10Vdc/4~20mA/24VAC, 10~ 40mm Stroke

ALX67.XXX

#### Type designation





#### Description

Electrical actuator, raise lower travel is adjustable from 15~50mm by pressing start butten while initialization process. Control signals 0...10Vdc or 4..20mA are select -able on the PCB to meet the conventional controllers or DDC/PLCs connected to central supervisory system.

### Application

In heating, ventilating, air conditioning and other industrial installations for control of 2-port or 3-port valves to be controlled by electrical remote control. signals from electronic controllers or DDC/PLCs.

## Ordering Example

When ordering, please give full designation and type

\* See summary of types

## Technical Data

Supply voltage Frequency Power source Power consumption

Running time Model of control Travel /raise lower Noise level

Nominal Torque Control signal(V) Voltage Current

Aux output signals Switching capacity Resistance

Permissible amb.temp. Operation

Transport & storage Permissible amb.humid. Protection class/ housing Max. medium temp. Cable entry glands

Estimated life time

-Drive motor -Gear train -Weight

-24Vav±20% 50/60Hz Synchronous motor

\*See summary of types Proportional(std) 10~ 40mm, adjustable <35[dB] 1800~ 4000Nf

0~10Vdc 4~20mA

10(3)A 24~250Vac **0~1000**Ω

-15...+50°C -30...+65℃

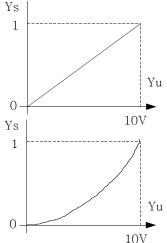
Class D to DIN40040 IP54 to DIN 40050 +80℃

PG11

40,000,000 cycles 80,000,000 cycles 2.2Kg

#### Function

The actuator is controlled by a standard signal of 0...10 Vdc/4~20mA received from electronic controller or DDC /PLC unit. It provides electronic position control.



Correlation between control signal and correcting variable.

Correlation between travel and volumetric flow

> Ys = Correcting variable  $Y_{u} = control signal .0..1OVdc$

 $Y_R$  = feedback signal 0...10V

 $V_{100}$  = volumetric flow  $H_{100}$  = Output travel

#### Summary of Types

20mm Stroke

Zonini Otroke								
Type Nr	Force	R-time	Aux.units					
Type IVI	Nf	60Hz	0 1 2 3					
ALX67.2251200	1200	200s	0 SW 140Ω 1000Ω					
ALX67.2251800	1800	200s	0 SW 140Ω 1000Ω					
ALX67.2252400	2400	200s	0 SW 140Ω 1000Ω					
ALX67.2253000	3000	200s	0 SW 140Ω 1000Ω					
ALX67.2253500	3500	200s	0 SW 140Ω 1000Ω					
ALX67.2254000	4000	200s	0 SW 140Ω 1000Ω					
ALX67.2255000	5000	200s	0 SW 140Ω 1000Ω					

40mm Stroke

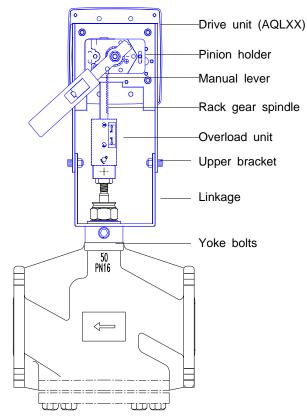
40mm Stroke	Force	R-time	Aux.units		
Type Nr	Nf	60Hz	0 1	2	3
ALX67.4261200	1200	400s	0 SW	<b>140</b> Ω	<b>1000</b> Ω
ALX67.4261800	1800	400s	0 SW	<b>140</b> Ω	1000Ω
ALX67.4262400	2400	400s	0 SW	<b>140</b> Ω	1000Ω
ALX67.4653000	3000	400s	0 SW	<b>140</b> Ω	1000Ω
ALX67.4263500	3500	400s	0 SW	<b>140</b> Ω	1000Ω
ALX67.4264000	4000	400s	0 SW	<b>140</b> Ω	1000Ω
ALX67.4265000	5000	400s	0 SW	<b>140</b> Ω	<b>1000</b> Ω

ATI-PI-ALX67-E

### **Design Features**

Actuators are supplied as separate units. Assemblying them requires neither special tools nor adjustments.

- Maintenance free electrical actuator with reversible synchronous motor.
- Selector switches are provided to change the direction of rotation or change of signals.
- A blockingproof gear train with self- lubrication sintered metal bearings make less troubles.
- Quick mounting bracket for diifferent devices make easy installation.
- Constant speed and output torque.
- Gear box is made of aluminum die cast and coated with special materials.
- Important gears are made of sintered metal and properly heat treated.



## **Application Advice**

For further information on the complete regulating unit consist of actuator and equipment to be operated also refer to the Data Sheet of the various type of valves,

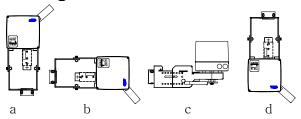
43000 ...44999.

Observe the permissible temperatures. For details refer to <Application > and <Technical Data>

Data Sheet 34001 contains basic system data on POLYTEK.

All hints and explanations given in this sheet must be observed.

### Mounting and Installation Advice

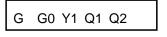


### **Commissioning Advice**

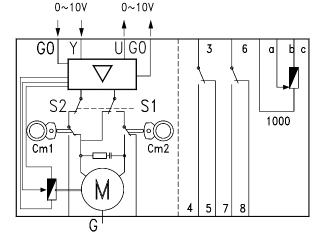
.When commissioning the installation, check the wiring and make a functional test.

Motor rotation can also be changed by changing the terminals as shown below.

#### Wiring diagram



## Internal Diagram



G0 = (SN)Ground

G = Supply(SP)

Y1 = Input signal

Q1 = Position (On)

Q2 = Position (Off)

U = Feedback

11 =switch contact

12 =switch contact

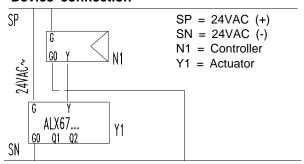
Cml =cam sw~top

Cm2 =cam sw~bottom

1 =Potentiometer 1

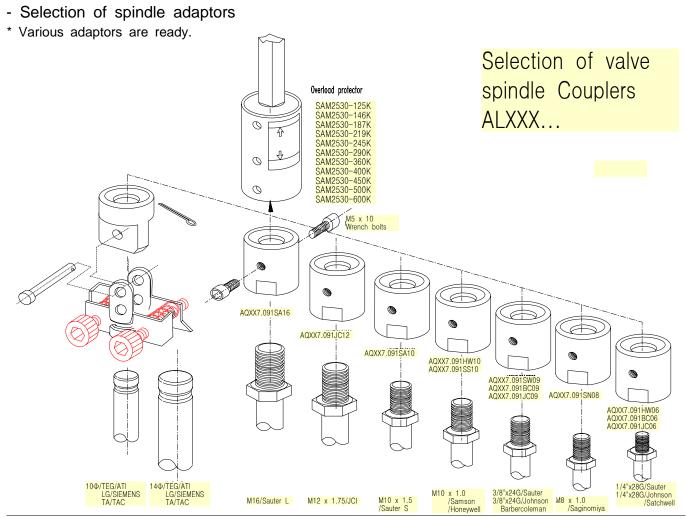
140R or 1000 Ω

#### **Device connection**

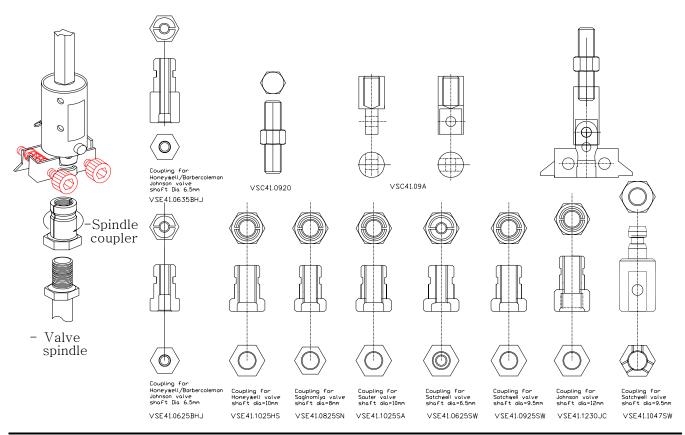


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#### **ACCESSORIES**

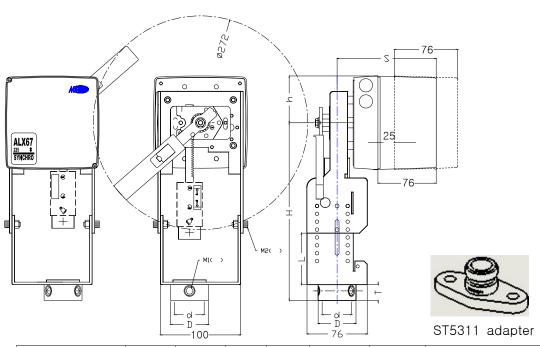


- Selection of spindle couplers
- \* ATI standard spindle couplers are made for all brands of valves in the control market.



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## **Dimension**



	d	Н	h	L	Т	M1	Remarks
ATI/TEG	44	~270	60	45/65	24.5	M8	* 2 STEP adjustable to stroke
Siemens	44	~270	60	45/65	24.5	M8	* 2 STEP adjustable to stroke
Honeywell	38	~270	60	35/45	22	M8	* 3 STEP adjustable to stroke
Johnson	50	~360	60	45/65	35	M8	* 5 STEP adjustable to stroke
Samson	30	~270	60	20/25	20	M5	* Valves without yoke
Sauter-S	38	~270	60	45	24.5	M8	* 1 STEP reduced stroke
Sauter-L	55	~360	60	85	35	M10	* 1 STEP reduced stroke
Satchwell	32	~360	60	45/65	24.5	M8	* 4 STEP adjustable to stroke
Siebe	32	~270	60	30/45	24.5	M8	* 3 STEP adjustable to stroke
Staefa	*	~360	60	45/85	24.5/35	M8/M10	* Not available for magnetic valves
Trend	48	~270	60	45	24.5	M8	* 3 STEP adjustable to stroke
RTK	*	~360	60	45/65	24.5	M8	* Require additional adapter
TA/TAC	44	~270	60	45	24.5	M8	* 3 STEP adjustable to stroke
YAMATAKE	38	~270	60	30/45	22	M8	* Only for raise/lower valves

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