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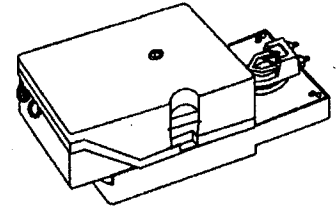
## Electric Rotary Actuators

Synchronous motor drives, 3-Position, 220Vac  
with Magnetic coupling safety system

# AQR35.1.

### AQR35.12120

- Aux. output 0= none 1=spst 2=140Ω 3=1000Ω 9=Converter
- Output Torque(Nm); 1=7.5N 2=15 3=20 4=30 9=Options
- Running time; 1=120s 2=60s 3=30s 4=15s 5=10s 6=5s 9=Options
- Supply voltage
- 1=110Vac, 2=24Vac, 3=220Vac, 4=380Vac, 7=12Vdc, 8=24Vdc
- 1=Rotary 2=Linear 9=Options
- Version No.
- Input signal: 2=On/Off, 3=3-pos. 220Vac, 5=4..20mA 6=0..10Vdc
- 7=0..20Vdc, 8=3-pos. 24Vac, 9=0..135Ω
- R=Damper**
- Type of drive motor
- I= Induction, Q= Synchronous, S= Servo, U= DC, Z= Stepper
- Product group: **A= Actuator**



### Description

Electrical actuator, 3-position-forward-stop-reverse-control, rotating angle is 90° and magnetic coupling with mechanical limitation system without spring return.

### Application

In heating, ventilating, air conditioning and other industrial installations for control of air dampers, VAV terminals and other ventilating openings having up to 5m<sup>2</sup> to be controlled by electrical remote control. Relay signals are also acceptable.

### Ordering Specification

When ordering, please give full designation and type reference of unit;

Ex: AQR35.1212.0 Electrical Damper Actuator  
3-position control  
Rotary type, 220Vac, 120s, 15Nm  
for aux unit

### Technical Data

|                                |                               |
|--------------------------------|-------------------------------|
| Supply voltage                 | 220V ac ± 20%                 |
| Frequency                      | 50Hz, 60Hz                    |
| Power source                   | Synchronous motor             |
| Power consumption              | 3VA...                        |
| Running time                   | 125s at 60Hz.<br>150s at 50Hz |
| Model of control               | 3-Position                    |
| Travel /angular rotation       | 90°                           |
| Noise level                    | >35[dB] max.                  |
| Nominal Torque                 | 15Nm.constant                 |
| Torque limiter                 | Magnetic coupling             |
| Control signal                 |                               |
| Neutral (G0)                   | N (C)                         |
| Control signal(Y1)             | P1(A)                         |
| Control signal(Y2)             | P2(B)                         |
| Aux.output                     |                               |
| Resistance                     | 0...1000 (0...100%)           |
| Switching                      | 10(3)24...250Vac              |
| Weight                         | 1.Kg                          |
| Permissible amb.temp.          |                               |
| Operation                      | -15...+50°C                   |
| Transport & storage            | -30...+65°C                   |
| Permissible amb.humid.         | class D to DIN 40040          |
| Protection standard of housing | IP54 to DIN 40050             |
| Max. medium temp.              | +150 °C                       |
| Cable entry glands             | PG11                          |

### Accessories;

|                          |                    |
|--------------------------|--------------------|
| position indication unit |                    |
| -potentiometer           | -0...140Ω          |
| -potentiometer           | -0...1000Ω         |
| position alarm switch    |                    |
| -snap action switch      | 10(3)A 24...250Vac |

### Estimated life time

|              |                   |
|--------------|-------------------|
| -Drive motor | 40,000,000 cycles |
| -Gear train  | 80,000,000 cycles |

### Summary of types

| Type Nr.    | Output Torque | Running time |      | Space for Aux.units |    |            |
|-------------|---------------|--------------|------|---------------------|----|------------|
|             |               | 50Hz         | 60Hz | 0                   | 1  | 2 3        |
| AQR35.12110 | 7.5Nm         | 150s         | 125s | 0                   | SW | 140Ω 1000Ω |
| AQR35.12120 | 15.0Nm        | 150s         | 125s | 0                   | SW | 140Ω 1000Ω |
| AQR35.12130 | 20.0Nm        | 150s         | 125s | 0                   | SW | 140Ω 1000Ω |
| AQR35.12140 | 30.0Nm        | 150s         | 125s | 0                   | SW | 140Ω 1000Ω |
| AQR35.12210 | 7.5Nm         | 72s          | 60s  | 0                   | SW | 140Ω 1000Ω |
| AQR35.12220 | 15.0Nm        | 72s          | 60s  | 0                   | SW | 140Ω 1000Ω |
| AQR35.12230 | 20.0Nm        | 72s          | 60s  | 0                   | SW | 140Ω 1000Ω |
| AQR35.12240 | 30.0Nm        | 72s          | 60s  | 0                   | SW | 140Ω 1000Ω |

### Function

The actuator is controlled by a standard signal of 3-position On/Off relay received from conventional electro-mechanical switch of temperature, pressure, level, etc., or from conventional electronic switching controller or DDC unit. It provides electronic position control which, in conjunction with ATI or any compatible paddle type air dampers or air valves.

|                    |                                |
|--------------------|--------------------------------|
| Power supply to Y1 | : rotate forward               |
| supply to Y2       | : rotate reverse way           |
| disconnect power   | : remain still at the position |

This type of actuators can be used for time based pulse output signal for P, PI, PID controls such as DDC or PLC supervisory system.

For slave control of series connection of many units you must use potentiometer.

### Auxiliary units

Reference output any combination of following.

- 0...1000Ω resistance signal allows indication of position.
- On / Off switching units

## Design Features

Actuator are supplied as separate units. Assembling them requires neither special tools nor adjustments.

- Maintenance free electrical actuator with reversible synchronous motor
- A switch on PCB can reverse the rotation of the actuator.
- Blocking proof gear train with self-lubrication sintered bearings
- Quick mounting bracket make easy installation.
- Constant speed and constant power-torque-
- Contactless coupling insures long life and quite operation.
- Gear train is made of aluminum die-cast and specially coated for corrosion proof.
- Important gears are made of sintered metal or special tool steel and heat treatment.

Data Sheet 34001 contains basic system data on POLYTEK. All hints and explanations given in this sheet must be observed.

All units connected to terminals Y and U, together with the AQR..., must be connected to the same G0.

The factory fitted link across terminals R and M may be removed only if a unit is connected between these terminals.

## Mounting and Installation Advice

Mounting positions:

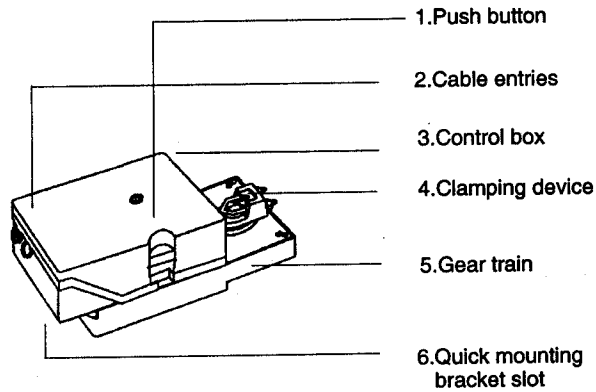
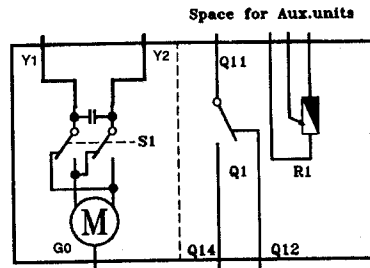
The actuator's mounting instructions are supplied in the box of the unit.

## Commissioning Advice

When commissioning the installation, check the wiring and make a functional test.

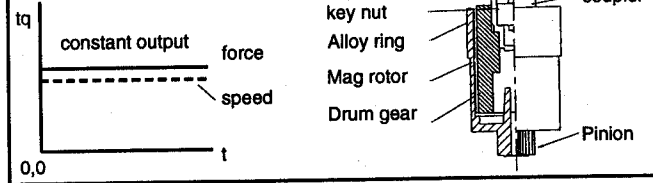
## Wiring Diagram

Internal Diagram



## Special features

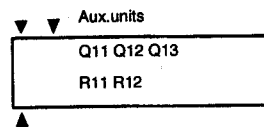
Utilizing hysteresis coupling technology gives more safer operation of actuators by providing constant output force and speed.



## Application Advice

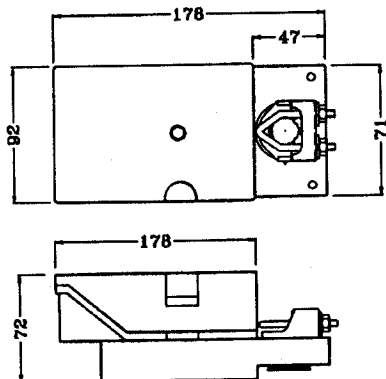
For further information on the complete regulating unit consist of actuator and valve also refer to the Data Sheet of the various type of valves, 43000... 44999. Observe the permissible temperatures. For details refer to <Application > and <Technical Data>

## Connecting terminals



- Y1 = Operating voltage P1
- Y2 = Operating voltage P2
- G0 = G0=system neutral(SN)
- Q11 = Switch common
- Q12 = Normal close
- Q13 = Normal open
- R11 = Measuring neutral
- R12 = 0...1000

## Dimensions



Dimensions in mm

We reserve the right to make changes and improvements in our products which may affect the accuracy of the information contained in this leaflet.